

Package ‘Convolutioner’

October 12, 2022

Type Package

Title Convolution of Data

Version 0.1.0

Maintainer Federico Maria Vivaldi <federico-vivaldi@virgilio.it>

Description General functions for convolutions of data. Moving average, running median, and other filters are available.

Bibliography regarding the functions can be found in the following text.
Richard G. Brereton (2003) <ISBN:9780471489771>.

License GPL-3

Encoding UTF-8

LazyData true

RoxygenNote 7.1.1

NeedsCompilation no

Author Federico Maria Vivaldi [aut, cre]

Repository CRAN

Date/Publication 2021-03-11 10:40:02 UTC

R topics documented:

Hamming	2
Hann	2
MA	3
RMS	4
sine	4
test_data	5

Index	6
--------------	----------

Hamming

Hamming window filter.

Description

This function return the data smoothed using the an Hamming window filter. Data are smoothed using a cosine window with particular coefficients.

Usage

```
Hamming(raw_data, buffer_size = 5)
```

Arguments

raw_data	Data upon which the algorithm is applied
buffer_size	number of points the algorithm use to compute the coefficients of the Hann window

Value

Smoothed data using Hann Window filter

Examples

```
raw_data = c(1:100)
smoothed_data = Hamming(raw_data)
```

Hann

Hann window filter.

Description

This function return the data smoothed using the an Hann window filter. Data are smoothed using a cosine window.

Usage

```
Hann(raw_data, buffer_size = 5)
```

Arguments

raw_data	Data upon which the algorithm is applied
buffer_size	number of points the algorithm use to compute the coefficients of the Hann window

Value

Smoothed data using Hann Window filter

Examples

```
raw_data = c(1:100)
smoothed_data = Hann(raw_data)
```

MA

Moving average filter.

Description

This function return the data smoothed using the basic moving average algorithm. For each chunk of data of size equal to the `buffer_size` parameter is calculated the average and this value is used as the `i` term of the newly smoothed data. zero padding is applied for initial and final values

Usage

```
MA(raw_data, buffer_size = 5)
```

Arguments

<code>raw_data</code>	Data upon which the algorithm is applied
<code>buffer_size</code>	number of points the algorithm use to compute the average

Value

Smoothed data using moving average algorithm

Examples

```
raw_data = c(1:100)
smoothed_data = MA(raw_data)
```

RMS

Running median smoothing.

Description

This function return the data smoothed using the running median algorithm. For each chunk of data of size equal to the `buffer_size` parameter is calculated the median and this value is used as the `i` term of the newly smoothed data. For initial and final values zero padding is applied.

Usage

```
RMS(raw_data, buffer_size = 5)
```

Arguments

<code>raw_data</code>	Data upon which the algorithm is applied
<code>buffer_size</code>	number of points the algorithm use to compute the median

Value

Smoothed data using running median algorithm

Examples

```
raw_data = c(1:100)
smoothed_data = RMS(raw_data)
```

sine*Sine window filter.*

Description

This function return the data smoothed using the a sine window filter.

Usage

```
sine(raw_data, buffer_size = 5)
```

Arguments

<code>raw_data</code>	Data upon which the algorithm is applied
<code>buffer_size</code>	number of points the algorithm use to compute the coefficients of the Hann window

Value

Smoothed data using Hann Window filter

Examples

```
raw_data = c(1:100)
smoothed_data = sine(raw_data)
```

test_data	<i>Test data generator</i>
-----------	----------------------------

Description

Generate test data in order to test the filtering functions. To a signal function is added random noise contribution. V0.1 = noise is assumed gaussian

Usage

```
test_data(
  amplitude = 1,
  f = 100,
  npoints = 1000,
  type = "sinusoidal",
  x0 = 0,
  noise_contribution = 100
)
```

Arguments

amplitude	amplitude of the signal, default = 1
f	frequency of the sinusoidal signal, default = 100
npoints	number of points of the time serie
type	type of signal, default = sinusoidal. Available types: sinusoidal, gaussian
x0	signal position for gaussian type. Default = 0
noise_contribution	percentage pointing the maximum wanted signal/noise ratio. Default = 10

Value

A time serie with added random noise.

Examples

```
test_data()
```

Index

Hamming, [2](#)

Hann, [2](#)

MA, [3](#)

RMS, [4](#)

sine, [4](#)

test_data, [5](#)